



**Course Level**

**IFP Initial**

**PANS-OPS Basic online**

<b>Duration</b>	At student's discretion	Recommended to complete within a year
<b>Tuition Fee</b>	CHF 10000 per participant	
<b>Instructors</b>	Beat Zimmermann (IFP)	Romano Germann (IFP practical)
<b>Certificate</b>	ANI Certificate	

<b>Questions at a glance</b>	<b>Answer</b>
<b>ICAO recognised?</b>	No, there is no such thing as an ICAO recognition for training. ANI is a State-approved training provider and complies with all ICAO training regulations.
<b>Pre-requisites?</b>	Yes and no. Please see below for details.
<b>Why more expensive than Classroom Cours?</b>	The online course covers more material than the Classroom Course. Also you can spend longer time on a specific topic.
<b>Practical?</b>	Yes, required. Join a published Classroom Course or check for specific practical sessions arranged for online students.
<b>Is an instructor available for questions?</b>	Of course. Questions by email are always possible. It is also possible to set up a live coaching session via GoToMeeting.

## **1. ANI Procedure Design Training Program and Concept**

All ANI Procedure Design/PANS-OPS courses cope with ICAO document 9906 "Quality Assurance Manual For Flight Procedure Design", vol. II "Flight Procedure Designer Training".

## **2. General Concept of the Online Course**

According to ICAO doc. 9906, vol. II, Flight Procedure Designer Training must be competency based. This results in a fundamental difference from traditional education. Traditional education is centered on the teacher and the unit of progression is time. In other words, the class will progress to the next topic whenever the teacher says so. It is up to the student to understand the material in the allocated time.

In competency based education however, the teaching is centered on the learner and the unit of progression is the mastery of the skill. That leads to the conclusion that everybody in the class must understand and prove mastery before progressing to the next topic.

This is no problem when the timeframe of the education is not limited. Typical examples of competency based education are the training for the Private Pilot's License or musical instrument education. The progress is tailored to the learner.

The online PANS-OPS basic course is competency based training in its pure form. The learner dictates the pace of progress and only continues when the skill is mastered and feedback received from the instructor. Hence Online training allows to progress at a personal pace and spend more time on a specific topic than in a class. However, online training should only be chosen by students who are experienced with disciplined self-learning.

## **3. Pre-requisites**

ICAO doc. 9906 vol. II specifies pre-requisite Skills, Knowledge and Attitudes (SKAs) for initial training. When the student complies with these, reasonable assurance exists that the individual topics and skills will be mastered in a given time. Basically for the online course, these requirements can be relaxed to a certain level, as the student has the option to stop a lecture and establish the required knowledge first. Example: In a lecture the theorem of Sines is mentioned. The learner does not know that theorem. He can stop the lecture and get the appropriate information first and then continue.

## **PRE-REQUISITE SKAS**

(extract from ICAO do. 9906, vol. II)

### 3.3.1 Mathematics

#### 3.3.1.1 Algebra

Students should be competent in Algebra to at least the level of resolving equations with 2 unknowns and handling operations of the 3rd level (Exponentiation, Radical, Logarithms, Angular functions). This requirement will assure the understanding of formulas given in the relative criteria documents as well as the ability to follow rationales, on which certain criteria are based.

#### 3.3.1.2 Geometry

Students should be familiar with the classical Euclidian Geometry (Plane Geometry, Solid Geometry) as well as Thales and Pythagoras constructions.

#### 3.3.1.3 Trigonometry

Students should be competent in all Trigonometry Functions such as Sine, Cosine, Tangent, Cotangent, Secant and Cosecant. Furthermore they should be familiar with Trigonometry Theorems such as the Theorem of Sines and the Theorem of Cosines.

#### 3.3.1.4 Probability and Statistics

Students should have basic knowledge of Statistical and Probability Mathematics, particularly an understanding of the Gaussian (Normal) distribution.

### 3.3.2 Aviation or Aviation-related pre-requisites

The job profile of an Instrument Flight Procedure Designer requires knowledge in various fields of activity in aviation. Training providers are encouraged to offer ab-initio training and that the following prerequisites are met by the student so as to ensure that the length of training can be optimized.

#### 3.3.2.1 Air Traffic Management

Students should demonstrate fundamental knowledge of Air Traffic Management (ATM) as in ICAO doc. 4444 (PANS-ATM), as well as understanding the broad concept of ATM which consists of ATS including ATC (Air Traffic Control), ATFM (Air Traffic Flow Management) and ASM (Airspace Management), other fields related to ATM such as route spacing, ATC separation, aviation weather, etc.

#### 3.3.2.2 Navigation, Navigation Systems and Geography

Students should demonstrate knowledge of Navigation, Navigation Systems and Geography to the level of any pilot's licence with Instrument Rating (IR). It is however not a requirement to hold such a license.

#### 3.3.2.3 Aircraft Operations

Students should demonstrate knowledge of the basics of flying and aerodynamics. It is however not a requirement to hold a pilot's license.

#### 3.3.2.4 Aircraft Performance

Students should demonstrate knowledge of Aircraft Performance to the level of any pilot's license with Instrument Rating (IR). It is however not a requirement to hold such a license.

#### 3.3.2.5 Aeronautical Information Services

Students should demonstrate fundamental knowledge of Annex 15 (Aeronautical Information Services).

#### 3.3.2.6 Aerodrome safeguarding

Students must be familiar with the basic requirements for aerodrome safeguarding (Annex 14 Obstacle limitation surfaces, Aerodrome reference codes).

#### 3.3.2.7 Geodesy

Geodesy, also called geodetics, is the scientific discipline that deals with the measurement and representation of the earth, its gravitational field and geodynamic phenomena (polar motion, earth tides, and crustal motion) in three-dimensional time varying space. Geodesy is primarily concerned with positioning and the gravity field and geometrical aspects of their temporal variations, although it can also include the study of the Earth's magnetic field.

Students should demonstrate fundamental knowledge in the following areas of Geodesy:

- Geoid and reference ellipsoid
- Coordinate systems in space
- Coordinate systems in the plane
- Heights
- Geodetic Datums and Datum conversion • Point positioning
- Units and measures on the ellipsoid
- Geodetic Principal Problem
- Geodetic Inverse Problem

#### 3.3.3 Language

In order to progress through the competency-based training outlined above, trainees need to demonstrate their ability to achieve terminal objective related to the competency elements. As training will be delivered within a certain timeframe, it is important that trainees learn the material within the time allocated. For this reason, proficiency in the language in which training will be delivered (instruction and training materials) is essential.

For courses in English, it is suggested that training providers require a score of 550 in the written TOEFL (Test of English as a Foreign Language), 213 in the TOEFL Computer Based Test, 79 in the TOEFL Internet Based Test and 750 in TOEIC (Test of English for International Communication) for students whose native language is not English. Alternatively, a score of 6.5 in the IELTS Academic Module (International English Language Testing System) can be accepted. Students

having studied at an English speaking institution for one year or longer can be exempted from providing a TOEFL or IELTS score.

(end of extract)

Note: For ANI courses, an ICAO language proficiency Level 5 is also accepted. Level 4 is not sufficient to understand the lectures.

## 5. Training Phases

The above pre-requisite SKAs refer to entry into "initial training", which according to doc. 9906 is the first time that a Flight Procedure Design Student gets in touch with actual Flight Procedure Design criteria. Any required training to get to that level is called "ab-initio". Initial Training **MUST** be followed by an On-the-Job (OJT) training phase. The length of such a phase can be specified by the PDSP (Procedure Design Service Provider). Typically an OJT phase will not be shorter than 15 weeks.

## 6. Initial Training Program

The ANI initial training program consists of 2 levels.

Level 1: All basic concepts, non-precision approach design, departures, holdings, en-route, all according conventional ground-based navigation

Level 2: PBN concept, PBN non-precision approaches, PBN departures and holdings, ILS (also in combination with PBN).

Due to the complexity and the quantity of the material in PANS-OPS, APV-Baro VNAV, SBAS-APV and GBAS criteria as well as RNP and RNP AR (Authorisation Required) criteria are classified „advanced“ and are NOT part of the initial training but are part of the advanced training concept.

## 7. OJT

An OJT phase must be provided by the employer, allowing the student to apply his skills in a practical environment. This must be under the supervision of a trained and experienced Flight procedure Designer.

## 8. Course Rundown

Topic	Description	Level
<b>Introduction</b>	What is the task „Flight Procedure Design“ about? Issues and Challenges.	1
<b>Situational Awareness</b>	Knowing the environment for which a procedure is developed. Obstacle situation, databases, vegetation.	1
<b>The PANS-OPS</b>	Who writes the criteria, how do they make their way into PANS-OPS. ICAO history and document levels.	1
<b>IFP basics</b>	Principles used in Flight Procedure Design. Tolerances of Navigation Signals and Flight Technical Errors.	1
<b>Annex 14 OLS</b>	Obstacle Limitation process around airports. Effect on procedures.	1
<b>Unit Conversions</b>	Conversions between typical aviation units and SI-Units.	1
<b>General Principles</b>	Some principles used in the design of procedures. Normal operations, rounding etc.	1
<b>IAS to TAS</b>	Conversions from IAS to True Air Speed	1
<b>Segments on an NPA</b>	Segments possibly existing in Non-Precision Approaches.	1
<b>Terminal Area Fixes</b>	Types of Fixes used in the Terminal Area. Explanation of some Legacy type fixes (Markers, Radar).	1
<b>Turn Calculations</b>	Newton’s Law of Circular Motion. Calculations of turn radii, Rate of turn.	1
<b>Turn Protection</b>	Protection of turns with wind influence. Omnidirectional wind, wind spirals and bounding circles.	1
<b>Aircraft Categories</b>	Categorization of Aircraft based on Threshold Speed.	1
<b>Arrival Segment</b>	Navigation and restriction for implementing an Arrival Segment. Protection Areas and Obstacle Clearance	1
<b>Initial Approach Segment</b>	Initial Approach concepts. Straight, DME Arcs and Reversal Procedures. Construction of Protection for Procedure Turns, Base Turns and Racetrack/Holding Patterns.	1
<b>Initial Approach with DR</b>	More efficient layouts with dead reckoning tracks on Initial Approach.	1
<b>Intermediate Segment</b>	Intermediate Segment protection and Obstacle Clearance.	1
<b>Final Approach Segment</b>	Possibilities to apply Final Approaches. Criteria to define straight-in minima. Protection and Obstacle Clearance.	1
<b>Missed Approach Segment</b>	Calculation of Start of Climb. Obstacle assessment in straight missed approaches. Construction methods for turning missed approaches. Turn at a point, turn at an altitude.	1

Topic	Description	Level
<b>Circling</b>	Constuction and obstacle assessment for circle-to land minima.	1
<b>Minimum Sector Altitudes</b>	Definition of sectors, Obstacle assessment and publication.	1
<b>Charting/AIP</b>	Chart titles, published information for approaches. Some examples.	1
<b>Departures</b>	Principles for establishing departure routes. Obstacle assessment, climb gradients and clean-up altitudes.	1
<b>Omnidirectional Departures</b>	Departures for remote locations with no Navigational Aids.	1
<b>Guidance on parallel OPS</b>	Segregated and parallel operations. How to separate Departure between them and Departures against missed approaches.	1
<b>Holding</b>	Application of Holding Templates on a VOR/DME Fix. Inbound to and outbound from the station.	1
<b>Area Navigation Introduction</b>	History of Area Navigation Methods and Systems.	2
<b>Are Navigation Basics</b>	Basic Concepts in Area Navigation.	2
<b>ARINC 424 Path/Terminators</b>	ARNINC 424 Database concepts.	2
<b>PBN Concept</b>	The ICAO PBN Concept. History and available Navigation Specifications and their purpose.	2
<b>Navigation Sensors in PBN</b>	Theory and System behaviour of VOR/DME, DME/DME and Basic GNSS Navigation.	2
<b>Protection Concept</b>	Protection Areas for PBN.	2
<b>T/Y Bar Layout Concept</b>	Layout concept for approaches that reduces track miles for operators.	2
<b>Terminal Arrival Altitude</b>	Flexible Arrival Concept if no STARS are used.	2
<b>PBN Turn Protections</b>	Protection technique for PBN turns based on the path/ Terminator concept.	2
<b>PBN Departures</b>	PBN specifics when developing departure procedures.	2
<b>PBN Holdings</b>	Holding technique in PBN, protection and obstacle clearance.	2
<b>ILS General Principles</b>	Introduction to ILS Systems, Precision approach operations.	2
<b>Linear Surface Equation</b>	Calculating height on linear surfaces with reference to a specific point.	2
<b>Precision Segment Basic ILS</b>	Obstacle assessment with Basic ILS Method	2
<b>OAS Cat I</b>	Obstacle Assessment with OAS Method for Cat. I	2
<b>OAS Cat II</b>	Obstacle Assessment with OAS Method for Cat. II	2
<b>Collision Risk Model</b>	CRM Theory and sample scenario.	2

Topic	Description	Level
<b>Legacy ILS Missed Approach</b>	Constructing missed approach with legacy navigation after ILS.	2
<b>Refined ILS Missed Approach</b>	More efficient method for turning at an altitude after an ILS.	2
<b>LOC only</b>	Criteria for GP inop procedures.	2
<b>Offset ILS</b>	ILS Cat. I offset localizer alignment criteria.	2
<b>Parallel Approach OAS</b>	Assessing obstacles and break-out manoeuvres for parallel RWY ILS operations.	2
<b>PBN in combination with ILS</b>	Initial/Intermediate and Missed Approach in combination with ILS Final Approach.	2

## 9. Practical Project

A practical project on a real airport has to be worked under supervision of an instructor. Either a student joins a Classroom Course (two trips) or he can join a specific 2-week project set up for online students (scheduling depends on instructor availability).

Classroom; Last week of Part 1 is a Team Project on a real airport with a task to design a VOR Approach, a Departure Route and a Holding.

The last 7 working days of part 2 are a Team Project on a real airport with a task to design an approach to an LNAV minimum, a PBN departure and an ILS approach to Cat. I and Cat. II minima with PBN Initial/Intermediate and Missed Approaches.